Flimsy 3: PBN Navigation	Specification	Comparison
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Nav Spec	Environment	СОМ	Route	Required	Database,	<b>On-board</b>
			Spacing	Sensors	sequencing	monitoring
<b>RNAV</b> 1/2	All IFR	DCPC*	None specified	GNSS; or	Yes	No but
(P-RNAV)	En-route		+2 -	DME/DME; or		present
	RNAV 1 SIDs			VOR/DME;		with GNSS
	STARs with surveillance			DME/DME/IRU		
RNAV 5	Low-end	VHF	None specified	GNSS; or	Database	No but
(B-RNAV)	IFR aircraft	only	+1	DME/DME; or	optional but	present
	En-route with			VOR/DME;	waypoints	with GNSS
	surveillance			DME/DME/IRU	capability	
					required	
RNP 1	All IFR	DCPC*	3NM with	GNSS or	Yes	Yes
	SIDs STARs		surveillance	GNSS/IRU		
RNP 2	All IFR	DCPC*	15NM LAT	GNSS; or	Yes	Yes
	En-route		20NM LONG	GNSS/IRU		
	Category R		7-10NM			
	airspace		Terminal			
	en-route		$(Draft)^{+3}$			
	(dual systems					
	required)					
RNP 4	Category R/S	CPDLC	With CPDLC	GNSS or	Yes	Yes
	en route		and ADS-C:	GNSS/IRU		
			30NM LAT			
			30NM LONG			

\*VHF and CPDLC

<sup>+1</sup> Europe uses 18NM reciprocal direction, 16.5NM same direction with surveillance, 10NM special cases

<sup>+2</sup> Republic of Korea demonstrated high density 8NM parallel spaced routes with surveillance met TLS

<sup>+3</sup> Australia uses 7NM CEP en-route (=15NM spacing) in procedural airspace, 5NM with surveillance

Notes:

- 1. RNAV 5 does not require a navigation database but the system must have the capability of creating a flight plan with at least 4 waypoints. If a navigation database is used, the standard database management criteria should be applied.
- 2. *RNAV 5, RNAV 1 and RNAV 2 are intended for use in a surveillance environment but may be used for short durations without surveillance.*
- 3. RNAV 2 is a low accuracy version of RNAV 1.
- 4. RNP 4 is a navigation specification that is normally used to achieve reduced separation in a category R airspace environment that requires CPDLC and ADS-C.